

Monday 6 February

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Recap

Law of law numbers

$$\bar{X}_R = \frac{1}{R} \sum_r X^{(r)} \approx \mu \quad R \gg 1$$

Central limit theorem

$$p(s) \approx \frac{1}{\sqrt{2\pi N \sigma^2}} \exp \left[-\frac{(s - \mu)^2}{2N\sigma^2} \right] \quad N \gg 1$$

gaussian prob dist. ↙ single rep

Plan

Random walks & diffusion via CLT

Ensembles & equilibrium

Random walk

General modelling tool

Brownian motion, roulette, genetic drift, stock prices

Object takes random step

current position (state) $\rightarrow$ new position (state)

"Markov process" produces Markov chain

Simple example

1) One dimension — step ⁺ right probability p
step ⁻ left probability $q = 1 - p$

2) Fixed step length $l = 1$

3) Regular time interval Δt

total time $t = N\Delta t$ For N steps

Representative walk

L R L R R R

$N = 6$

final position $x = 2$

from starting $x = 0$

R L R L L L

$x = -2$

How many walks with $N = 6$?

$$2 \cdot 2 \cdots 2 = 2^N = 2^6 = 64$$

$$P(\text{LRLRRR}) = \frac{1}{64} \text{ iff } p = \frac{1}{2} = q$$

$$qppppp = p^4 q^2$$

$$P(\text{RLRLLL}) = p^2 q^4$$

Generic prob. for N -step walk with r steps to the right
 $N - r$ steps to the left

$$P_r = p^r q^{N-r}$$

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Compute expected final position $\langle x \rangle$ and $\langle x^2 \rangle - \langle x \rangle^2$
fluctuations

$$x = (+1)r + (-1)(N-r) = 2r - N$$

$$\text{Checks: } 2 \cdot 4 - 6 = 2 \quad 2 \cdot 2 - 6 = -2 \quad \checkmark$$

$$-N \leq x \leq N$$

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$P(x)$ equivalent to $\underline{P_r}$ only because step size $l = 1$ fixed
not general

X unaffected by order of steps

How many ways to get $x=4$ from $N=6$?

$$\binom{N}{r} = \binom{6}{5} = 6$$

$$r = \frac{1}{2}(x+N)$$

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Overall $P(x=4) = P_5 = 6 p^5 q$

General $P_r = \binom{N}{r} p^r q^{N-r}$

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$$\langle x \rangle = \sum_x x P(x) = \sum_{r=0}^N (2r-N) P_r = 2 \langle r \rangle - N$$

$$\langle x^2 \rangle = \sum_r (2r-N)^2 P_r = 4 \langle r^2 \rangle - 4N \langle r \rangle + N^2$$

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Generating Function

$$T(\theta) = \sum_{r=0}^N e^{r\theta} P_r$$

Set $\theta=0$ $T(0) = 1$

$$\left. \frac{d}{d\theta} T(\theta) \right|_{\theta=0} = \sum_r \left. \frac{d}{d\theta} e^{r\theta} P_r \right|_{\theta=0} = \sum_r r e^{r\theta} P_r \Big|_{\theta=0} = \langle r \rangle$$

$$\left. \frac{d^n}{d\theta^n} T(\theta) \right|_{\theta=0} = \sum_r r^n e^{r\theta} P_r \Big|_{\theta=0} = \langle r^n \rangle$$

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$$\begin{aligned} T(\theta) &= \sum_r e^{r\theta} \binom{N}{r} p^r q^{N-r} = \sum_r \binom{N}{r} (e^\theta p)^r q^{N-r} \\ &= (e^\theta p + q)^N \end{aligned}$$

(binomial Formula)
 $(a+b)^N = \sum_i \binom{N}{i} a^i b^{N-i}$

$$T(0) = (p+q)^N = 1$$

$$\left. \frac{d}{d\theta} (e^\theta p + q)^N \right|_{\theta=0} = N (e^\theta p + q)^{N-1} e^\theta p \Big|_{\theta=0} = N p = \langle r \rangle$$

$$\begin{aligned} \frac{d^2}{d\theta^2} (e^{\theta p + q})^N \Big|_{\theta=0} &= \cancel{N} e^{\theta p} (e^{\theta p + q})^{N-1} + N(N-1) e^{\theta p} (e^{\theta p + q})^{N-2} e^{\theta p} \Big|_{\theta=0} \\ &= Np + N(N-1)p^2 = Np(1 + Np - p) \\ &= Np(Np + q) = \langle r^2 \rangle \end{aligned}$$

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$$\langle x \rangle = 2\langle r \rangle - N = 2Np - N = N(2p - 1)$$

$$\langle x^2 \rangle - \langle x \rangle^2 = 4\langle r^2 \rangle - 4N\langle r \rangle + N^2 - (2\langle r \rangle - N)^2$$

$$(4\langle r^2 \rangle - 4N\langle r \rangle + N^2)$$

$$= 4(\langle r^2 \rangle - \langle r \rangle^2)$$

$$= 4(N^2 p^2 + Npq - N^2 p^2) = 4Npq$$

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Sanity checks

	$\langle x \rangle$	$\frac{\langle x^2 \rangle - \langle x \rangle^2}{N}$
$\frac{p}{0}$	$-N$	0
1	N	0
$\frac{1}{2}$	0	N

general result ..

Diffusion

Recall $t = NAt \rightarrow N = \frac{t}{At}$

$$\langle x \rangle = \left(\frac{t}{At} \right) (2p - 1) = \frac{2p - 1}{At} t \equiv v_{dr} t$$

Expected Final position drifts

Drift velocity $v_{dr} = \frac{\langle x \rangle}{t}$

Similarly for fluctuations

$$\langle x^2 \rangle - \langle x \rangle^2 = 4 \left(\frac{t}{\Delta t} \right) p q = \frac{4pq}{\Delta t} t = (\Delta x)^2$$

↳ diffusion length

Law of diffusion

$$\Delta x \propto \sqrt{t}$$

$$\Delta x = D \sqrt{t}$$

↳ diffusion constant governs scale of fluctuations

For this simple example

$$v_{dr} = \frac{2p-1}{\Delta t}$$

$$D = 2 \sqrt{\frac{pq}{\Delta t}}$$

Examples ✓

Connecting diffusion to central limit theorem

$$p(x) = \frac{1}{\sqrt{2\pi N\sigma^2}} \exp \left[-\frac{(x - N\mu)^2}{2N\sigma^2} \right]$$

$$x = s = \sum_i x_i$$

$N \gg 1$

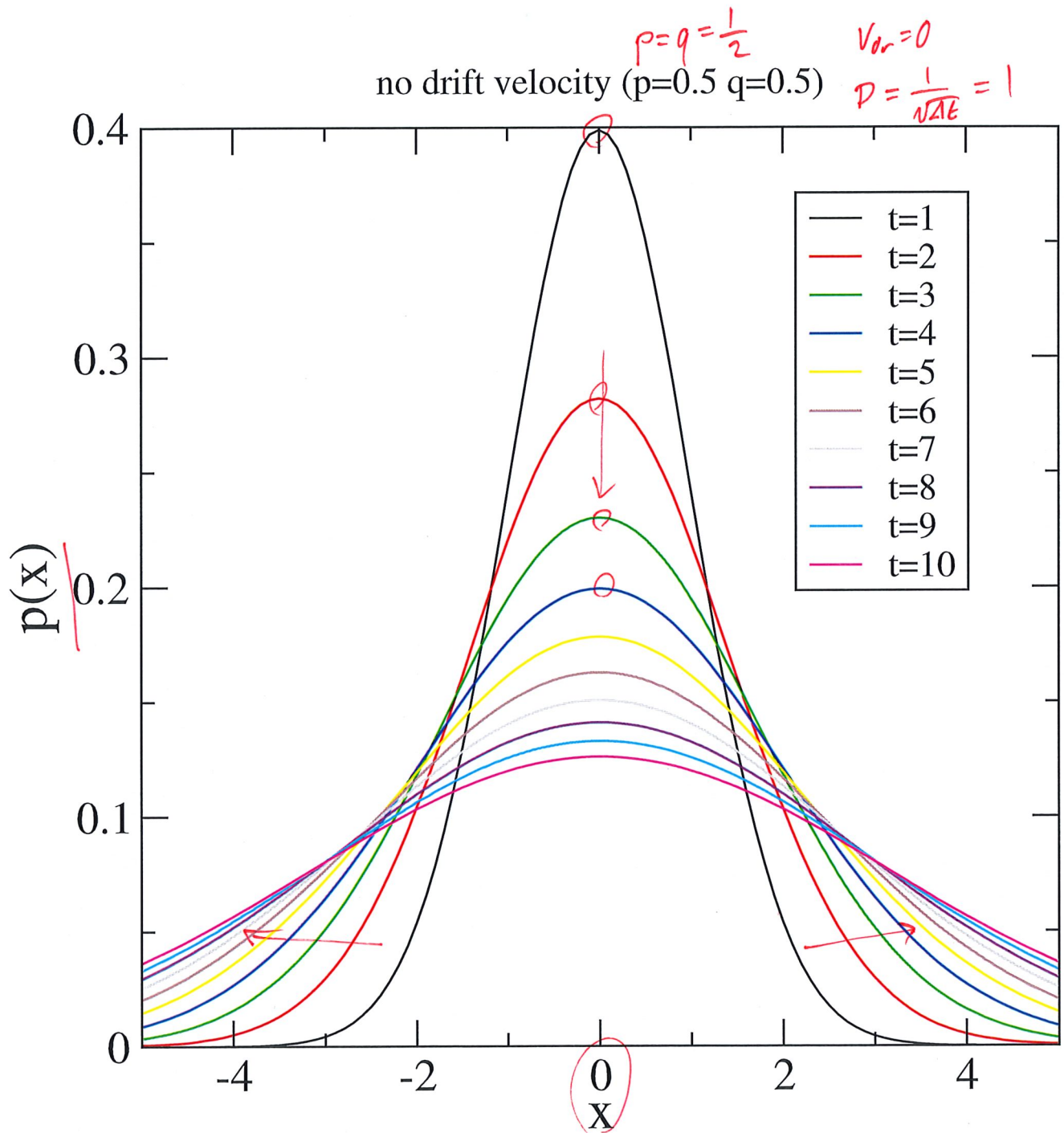
Mean μ and variance σ^2 of single-step process

$$\mu = \langle x_i \rangle = \sum_i x_i P_i = (+1)p + (-1)q = \frac{2p-1}{1-p} = v_{dr} \left(\frac{t}{N} \right) = \frac{v_{dr} \cdot t}{N}$$

$$\langle x_i^2 \rangle = (+1)^2 p + (-1)^2 q = 1$$

$$\sigma^2 = 1 - \mu^2 = 1 - (4p^2 - 4p + 1) = 4p(1-p) = \underline{4pq} = \frac{D^2 t}{N}$$

$$D^2 = \frac{4pq}{\Delta t} = \frac{\sigma^2 N}{t}$$

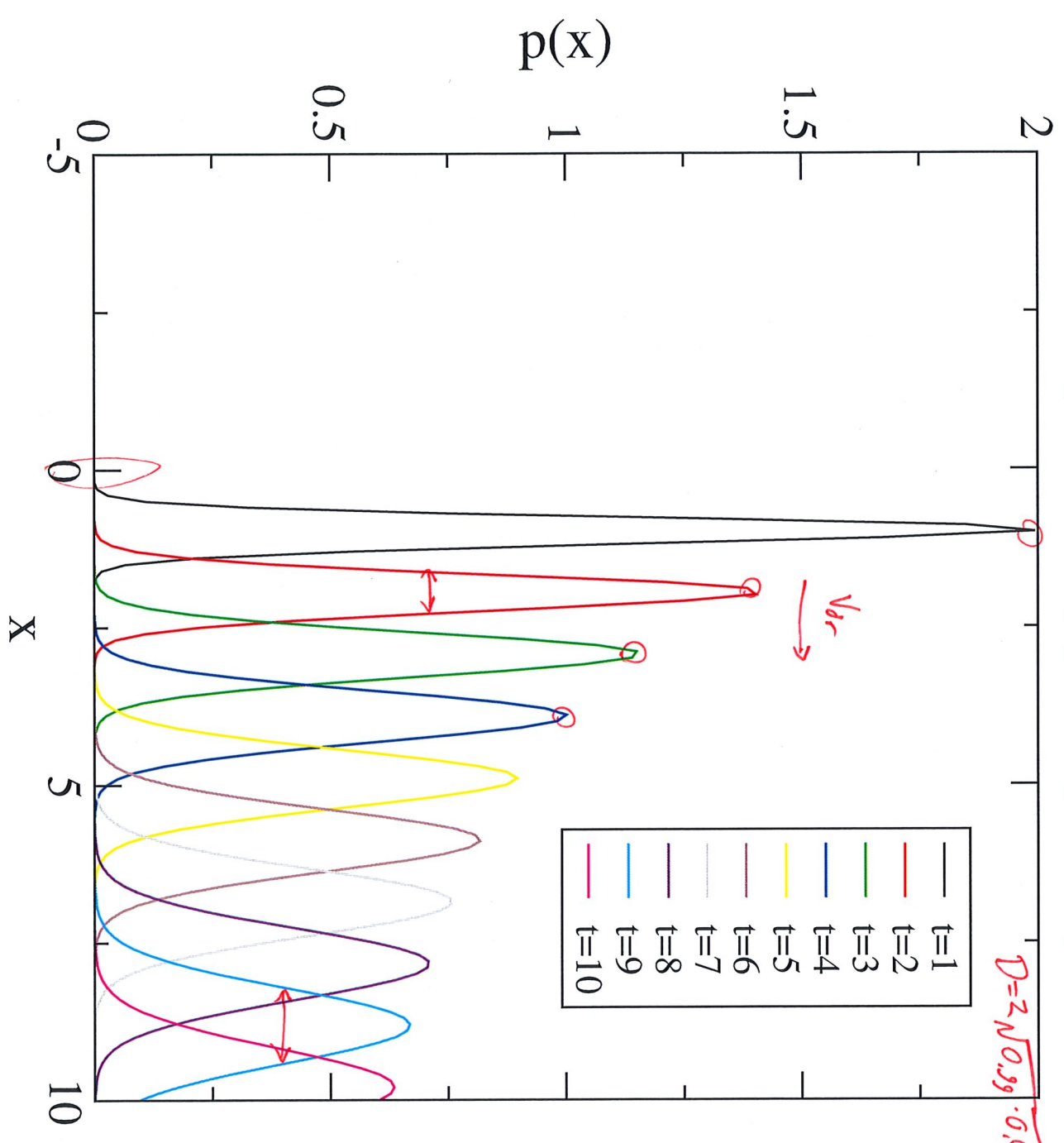


$\langle x \rangle = 0$

'one-sigma' interval $\sim 68\%$
 $-D\sqrt{t} \leq x \leq D\sqrt{t}$

high drift velocity ($p=0.99$, $q=0.01$) $V_{dr} = 2p-1 = 0.98$

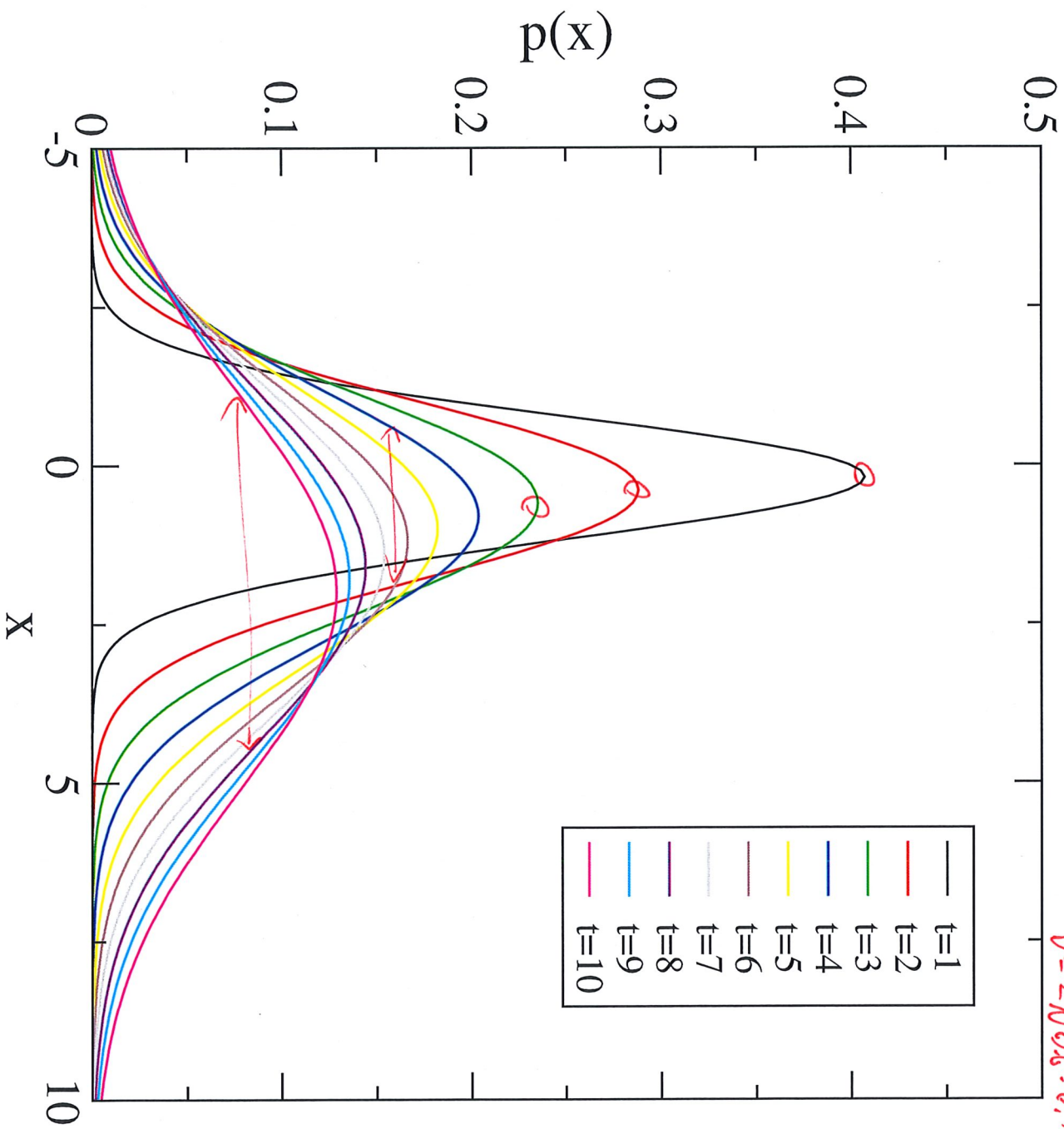
$$D = 2\sqrt{0.99 \cdot 0.01} \approx 0.198$$



low drift velocity ($p=0.6, q=0.4$)

$$V_{dr} = 0.2$$

$$D = 2\sqrt{0.6 \cdot 0.4} \approx 0.98$$



Resulting $N_M = v_{dr} t$ and $\sigma^2 = D^2 t$ are general
 (specific expressions w/p, q not general)

$$p(x) = \frac{1}{\sqrt{2\pi D^2 t}} \exp\left[-\frac{(x - v_{dr} t)^2}{2 D^2 t}\right]$$

peak at $x - v_{dr} t = 0$

width increases with $2 D^2 t$

→ normalization decrease $\sim D \sqrt{t}$

Drift vs. diffusion

Assuming $v_{dr} \neq 0$

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$$\left. \begin{array}{l} \langle x \rangle \propto t \\ \Delta x \propto \sqrt{t} \end{array} \right\} \frac{\Delta x}{\langle x \rangle} \propto \frac{\sqrt{t}}{t} = \frac{1}{\sqrt{t}} \rightarrow 0 \text{ as } t \rightarrow \infty$$

Although absolute diffusion length grows $\propto \sqrt{t}$
 relative uncertainty becomes negligible
 when compared to non-zero drift

Law of diffusion $\longleftrightarrow$ central limit theorem
 only assumes μ, σ^2 finite
 (single step)

Statistical

Statistical ensemble

General idea: Observe many particles evolving in time
subject to constraints
experiment
Different states w_i, w_j at different times t_i, t_j

Simple (but powerful) example: spin system

"particles" are spins that point up $\uparrow$ or down $\downarrow$

(motivation from magnetic molecules & much more)

Configuration of $N=8$ spins fixed in a line

$\uparrow \downarrow \uparrow \uparrow \uparrow \downarrow \uparrow \uparrow$

Total # of configs: $2 \cdot 2 \cdots 2 = 2^N = 2^8 = 256$

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Measure # of spins for all 256 configs always gives 8
 $\rightarrow N$ is conserved quantity same for all w_i

Another example: Total internal energy of isolated (closed) system
 $E(w_i) = E(w_j)$ for all i, j

First ~~experiment~~ observed empirically

"First Law of Thermodynamics"

Later proven through Emmy Noether (in flat space-time)

Equivalent state: Changing internal energy of system Ω

$\rightarrow$ equal & opposite change in energy
of its surroundings